

## On the Existence of Differentiable Solutions of a Functional Equation

by

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**Summary.** The functional equation on the existence of differentiable solutions of the functional equation

$$x(t) = f(x, x(t))$$

is due to H. Cartan (1927) (see also H. Cartan [1], p. 108). There it is assumed that  $f$  is defined in a neighborhood of the point  $(0, 0)$  in  $\mathbb{R}^2$  and  $f$  is assumed to satisfy the following conditions:

In the present paper we are concerned with the  $C^1$  solutions of the functional equation

$$(1) \quad x'(t) = f(x, x(t))$$

where  $x$  is an unknown function.

Let  $I$  be a real interval. The problem of the existence of  $C^1$  solutions to (1) on  $I$  was investigated by H. Cartan [1] (see also [2], Chap. IV) under the following hypotheses (A), (B), (C) and (D).

(A)  $f \in C^1(I^2; \mathbb{R})$ , and for a certain  $\delta > 0$  we have

$$(B) \quad \frac{\partial f}{\partial x} > \delta \quad \text{for } (x, y) \in I^2$$

(C)  $I$  is defined such that  $I^2$  is a region  $D$  containing the point  $(0, 0)$  such that  $\partial D \cap \{x=0\}$  has the form  $x=0, y \in (a, b)$  and  $\partial D \cap \{y=0\}$  is a nonempty set (closed and  $f \in C^1(I^2; \mathbb{R})$ ).

$$(D) \quad \left| f'(x, y) \frac{\partial f}{\partial x}(x, y) \right| < \delta$$

(E)  $f'(x, y) > \delta$  in a neighborhood of  $(0, 0)$ .

Define the function  $h_1(x) = f(x, 0)$  by the invariant relation

$$h_1(x, x, x) = \frac{\partial f}{\partial x}(x, x) \quad \text{and} \quad h_2(x, x, x) = \frac{\partial f}{\partial y}(x, x, x).$$

$$|x_{i+1} - x_i| \leq |f(x_i) - f(x_{i-1})| \leq \frac{L}{2^i} \leq \frac{L}{2^i} \sum_{j=0}^{i-1} \frac{L}{2^j} \leq \frac{L}{2^i} \sum_{j=0}^{i-1} 2^j = L.$$

So that  $x_i \rightarrow x \in L$ .

We denote by  $\Phi$  the class of functions  $\varphi$  defined on  $L$  such that the curve  $x \mapsto \varphi(x)$  has a LSC at  $x \in L$ , and  $\varphi(x) = 0$ .

We have the following (cf. [2], also [1], p. 18)

**Lemma.** Suppose that hypotheses (i) and (ii) are fulfilled. If  $\varphi \in \Phi$  is a  $C^1$ -solution of Eq. (1) in  $L$ , then we have

$$(H) \quad \varphi_{i+1} - \varphi_i \leq \varphi_i - \varphi_{i-1} \leq \varphi_{i-1} - \varphi_{i-2} \leq \dots \leq \varphi_1,$$

where

$$(H') \quad \varphi_i = \varphi^{2^i}(\varphi) \quad (i = 0, 1, \dots, k).$$

The following fundamental theorem is due to H. Cartwright [2] (see also [1], p. 18).

**Theorem 1.** If hypotheses (i), (ii), (H) and (H') are fulfilled, then for any system of values  $x_0, \dots, x_k$  satisfying Eqs. (1) there exists at least one  $C^1$ -solution  $\varphi \in \Phi$  of Eq. (1) in  $L$  (satisfying condition (H)).

Essentially the present author has proved [3] the following stronger result.

**Theorem 2.** If hypotheses (i), (ii), (H) and (H') are fulfilled, then for any system  $x_0, \dots, x_k$  satisfying Eqs. (1) there exists exactly one  $C^1$ -solution  $\varphi \in \Phi$  of Eq. (1) in  $L$  (satisfying condition (H)).

It turns out, however, that in Theorem 1 and 2 hypothesis (H) is superfluous. In fact, in this paper we shall prove the following

**Theorem 3.** If hypotheses (i), (ii) and (H') are fulfilled, then for any system of values  $x_0, \dots, x_k$  satisfying Eqs. (1) there exists exactly one  $C^1$ -solution  $\varphi \in \Phi$  of Eq. (1) in  $L$  (satisfying condition (H)).

**Proof.** Without loss of generality we may assume that  $0 \in L$ . From (ii) we have  $f(x) \geq f(0) = 0$ . Hence in view of Theorem 2 it is sufficient to consider the case that  $f(x) > 0$  in this case we have by (ii) the inequality  $\left| \frac{f(x)}{x} - f'(0) \right| < \delta$ . Consequently also (H) is fulfilled. If there is no other solution  $\varphi \in \Phi$  continuous on  $L$ , we shall prove that this solution is of class  $C^1$  on  $L$ . For this purpose we introduce the sequence of equations

$$(E) \quad x^{i+1} = f(x, x, \dots, x),$$

where

$$(E') \quad f(x) = f(x_0, x_1, \dots, x_k, x), \quad f'(0) = 0.$$

By view of Theorem 2, for every  $i = 0, 1, 2, \dots, k$ , Eq. (E) has exactly one solution  $x_i \in \Phi$  of class  $C^1$  in  $L$ , where  $x_i = f(x_0, x_1, \dots, x_k, x_i)$ . Thus we have

$$x_i \text{ fixed } [x_0, x_1, \dots, x_k], \quad i = 0, 1, \dots, k-1.$$

Differentiating both sides of this equality we have

$$x^2(x^2 - 1)^{-\frac{3}{2}} \{x^2 \alpha_1(x) + C\} + \frac{dx}{dx} \{x^2(x^2 - 1)^{-\frac{3}{2}} \} = \frac{dx}{dx} \{x^2(x^2 - 1)^{-\frac{3}{2}} \}.$$

The same that  $\alpha_1(x) = \frac{C}{x^2}$  satisfies the equation

$$(B) \quad y'' + 2y' + y = \frac{C}{x^2}.$$

where

$$x = x^2, \quad y = \frac{dx}{dx} \{x^2(x^2 - 1)^{-\frac{3}{2}}\} + C \frac{dx}{dx} \{x^2(x^2 - 1)^{-\frac{3}{2}}\} + \frac{C}{x^2}.$$

Now if we take  $C = 0$  uniformly in every compact subset of  $\mathbb{R}$ , the equation (B) tends to  $y'' + 2y' + y = 0$  uniformly in every compact subset of  $\mathbb{R}$ . It is clear that  $\alpha_1$  satisfies uniformly in the domain

$$\mathbb{R} \setminus \{x = 0\} \quad \frac{dx}{dx} \{x^2(x^2 - 1)^{-\frac{3}{2}}\} + C \frac{dx}{dx} \{x^2(x^2 - 1)^{-\frac{3}{2}}\} = 0,$$

in every compact set included in  $\mathbb{R} \setminus \{x = 0\}$  (where it shows the set of solutions). Hence

$$\left| \frac{dx}{dx} \{x^2(x^2 - 1)^{-\frac{3}{2}}\} + C \frac{dx}{dx} \{x^2(x^2 - 1)^{-\frac{3}{2}}\} - \alpha_1 \frac{dx}{dx} \{x^2(x^2 - 1)^{-\frac{3}{2}}\} \right| \rightarrow 0 \quad \text{for } x \in \mathbb{R} \setminus \{x = 0\}.$$

Therefore, for  $\{y = \frac{C}{x^2} \} \in \mathbb{R} \setminus \{x = 0\}$  is the unique solution of eq. (B) which is continuous in  $\mathbb{R} \setminus \{x = 0\}$ . However, this equation has three particular solutions  $\{y = \frac{C}{x^2} \}$  continuous in  $\mathbb{R}$ . Applying again the theorem on the continuous dependence of continuous solutions on  $\{y = \frac{C}{x^2} \}$  we obtain for  $\alpha_1(x) = \frac{C}{x^2} + C_1$  uniformly in every compact subset of  $\mathbb{R}$ . Since for  $\alpha_1(x) = \frac{C}{x^2}$ , this implies that  $\alpha_1(x) = \frac{C}{x^2} + C_1$  and  $\alpha_1(x) = \frac{C}{x^2}$  for  $x \in \mathbb{R}$ .

Using the previous differentiating equation (B) we can prove that  $\alpha_1(x) = \frac{C}{x^2} + C_1$  for  $x \in \mathbb{R} \setminus \{x = 0\}$ . Repeating the procedure above we obtain  $\alpha_1(x) = \frac{C}{x^2}$  throughout the proof.

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