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Actual Mathematics

The main properties of solutions of a functional equation

In the present paper we are concerned with the functional equation

$$(1) \quad f(x) = f(y) + f(x/y),$$

where $f(x)$ and $h(x)$, g are known real valued function of real variable and x, y is unknown.

We assume the following hypothesis

(H) $f(x)$ is defined and continuous in an interval (a, b) and

$$(2) \quad f(x) > 0, \forall x \in (a, b) \text{ for } x \in (a, b).$$

$f(x)$ and $g(x)$ is defined in a domain D such that $(x, y) \in D$ whenever, for every $x \in (a, b)$ and $y \in (a, b)$ $(x/y) \in D$. $f(x)$ is a strongly open interval (a, b) , where $a, b \in \mathbb{R}$, $a < b$.

(3) $f(x), g(x)$ is continuous in every $(a, b) \subset D$ and

$$(4) \quad f(x) > 0, \forall x \in (a, b) \text{ for } x \in (a, b) \text{ for } x \in (a, b).$$

holds in a neighbourhood of the point (x, y) .

We shall prove the following

Theorem. Let hypothesis (H)-(3) be fulfilled. Then equation (1) has exactly one solution f defined in (a, b) , continuous at $x=0$ and such that $f(0)=0$.

P. It is known, that if f is strictly increasing in (a, b) and $f(x) > 0$ is increasing with respect to other variable in D , then f is increasing in (a, b) . If, for every fixed $x, h(x)$, $g(x)$ is a strictly decreasing function of y , then f is strictly increasing in (a, b) .

$f(x)$ is strictly decreasing in (a, b) and $g(x)$ is strictly increasing in (a, b) is known. If f is increasing domain (a, b) , $g(x)$ is a strictly decreasing function of other variable in D , then f is convex in (a, b) .

Proof. We choose $x=0$ and $x=1$ it will that (1) holds in the set

$$D = \{(x, y) \in (a, b) \times (a, b) : x/y \in (a, b)\}.$$

By (2) we may assume that f has been chosen in such a manner that

$$(5) \quad f(x), f(x) > 0 \text{ for } x \in (a, b).$$

Let F be the set of functions φ defined on $(0, \infty)$, continuous on \mathbb{R} and such that $\varphi(x) = \varphi(1/x)$ for all $x > 0$.

The set F with the norm

$$\|\varphi\| = \int_0^1 |\varphi(x)| dx + \int_1^\infty |\varphi(x)| dx$$

is a complete metric space. We define the operators

$$(T\varphi)(x) = \int_0^1 \varphi(t) dt + \int_1^\infty \varphi(t) dt$$

for $\varphi \in F$. It follows from (1) that

$$(T^2\varphi)(x) = \int_0^1 \int_0^1 \varphi(t) dt + \int_1^\infty \int_1^\infty \varphi(t) dt.$$

Now, from (1) and (2) we get

$$\begin{aligned} (T^3\varphi)(x) &= \int_0^1 \int_0^1 \int_0^1 \varphi(t) dt + \int_1^\infty \int_1^\infty \int_1^\infty \varphi(t) dt \\ &\quad + \int_0^1 \int_1^\infty \varphi(t) dt + \int_1^\infty \int_0^1 \varphi(t) dt. \end{aligned}$$

Since and from (1) we see that $\int_0^1 \varphi(t) dt = \int_1^\infty \varphi(t) dt = \int_0^1 \varphi(t) dt = \int_1^\infty \varphi(t) dt$, $\int_0^1 \int_1^\infty \varphi(t) dt = \int_1^\infty \int_0^1 \varphi(t) dt$ we obtain

$$(T^3\varphi)(x) = 3 \int_0^1 \varphi(t) dt.$$

This proves that $\{T^n\}$ converges from point (1). Further, we have to show that (2) is

$$\int_0^1 \varphi(t) dt = \int_1^\infty \varphi(t) dt, \quad \int_0^1 \int_1^\infty \varphi(t) dt = \int_1^\infty \int_0^1 \varphi(t) dt.$$

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where

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Let φ be a continuous map. On account of Banach's theorem from point (1) and relation (3) F is a Banach space. The relation (3) is a complete contraction with the linear operator $(T, \varphi) \in F, \|\varphi\| \leq 1$, Banach (4).

Remark 1. In the book (5) Theorem 1.1 has been proved under the assumption of the continuity of $\varphi(x, y)$ in \mathbb{R} but Theorem 1.1 will remain valid without this assumption and the proof is the same, except that that the relation (3) must be continuous.

For the proof of (1) we define the space F_1

$$F_1 = \{\varphi \in F \mid \varphi \text{ is increasing in } (0, \infty)\}.$$

Let us take $\varphi(x) = \ln(x)$. Then, the completeness of F_1 and from (2) we get

$$\int_0^1 \ln(x) dx = \int_1^\infty \ln(x) dx.$$

For $\mu \in P_1$, we have

$$\mu(\mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C}))) = \mu(\mathcal{C}(\mathcal{C})).$$

Note that (3) and the maximality of $\mathcal{C}(\mathcal{C})$ do not imply

$$\mu(\mu \in \mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C}))) \Rightarrow \mu \in \mathcal{C}(\mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C})),$$

i.e., μ is increasing in (3). Since and from the first part of the proof it follows that $\mu \in P_1$. Since P_1 is a complete metric space, the unique solution μ satisfies an arbitrarly small error ϵ iff μ is ϵ near to P_1 . Thus μ is increasing in $\mathcal{C}(\mathcal{C})$. It is readily seen that μ is increasing in \mathcal{C} , all possible properties follow from the properties of \mathcal{C} and that μ is continuous in \mathcal{C} (usual topologies $\tau_{\mathcal{C}}$, i.e. $P_{\mathcal{C}}$ in $\mu \in \mathcal{C}(\mathcal{C})$). It follows from the continuity of μ that there exists a number $\epsilon > 0$, such that for $\nu \in P_{\mathcal{C}}$, ν is ϵ near to μ . Hence for $\nu \in P_{\mathcal{C}}$, $\nu \in \mathcal{C}(\mathcal{C})$ (see above)

$$\mu(\mu \in \mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C}))) \Rightarrow \mu \in \mathcal{C}(\mathcal{C}).$$

So, μ is monotone in (3). $\mu \in P_1$. This maximality completes the proof of the maximality of $\mu \in \mathcal{C}(\mathcal{C})$.

It is easy to see $\mu \in \mathcal{C}(\mathcal{C})$ has strictly increasing location of the variable x , then for $\nu \in P_{\mathcal{C}}$, $\nu \in P_{\mathcal{C}}$ we have

$$\mu(\mu \in \mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C}))) \Rightarrow \mu(\nu \in \mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C}(\mathcal{C}) \cup \mathcal{C}(\mathcal{C}))) = \mu(\mathcal{C}(\mathcal{C})),$$

which proves that μ is strictly increasing.

Lemma 1. It is not sufficient to suppose that $\mathcal{C}(\mathcal{C})$ is strictly increasing in the variable μ . For instance, the unique solution μ satisfies at $\mu \in \mathcal{C}$ of the equation

$$\mu(\mu \in \mathcal{C}(\mathcal{C}(\mathcal{C})))$$

is constant, and $\mathcal{C}(\mathcal{C})$ is strictly increasing with respect to μ .

For the proof of (1) we define the space $P_{\mathcal{C}}$

$$P_{\mathcal{C}} = \{\mu \in P_{\mathcal{C}} \mid \mu \text{ is convex in } (\mathcal{C}, \mathcal{C})\}.$$

From the general self-consistency of \mathcal{C} it and μ we get for $\mu \in P_{\mathcal{C}}$, $\mu \in P_{\mathcal{C}}$ and μ given by Lemma 1

$$\begin{aligned} \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) &= \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) = \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) = \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) = \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) \\ &= \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) = \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) = \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) = \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) \\ &= \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) = \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) = \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) = \mu \left(\frac{\mathcal{C}(\mathcal{C}(\mathcal{C}))}{1} \right) \end{aligned}$$

It is readily seen that $\mu \in P_{\mathcal{C}}$ is the class of distributions μ at $P_{\mathcal{C}}$ and all the preceding part of the proof. All members $\mu \in P_{\mathcal{C}}$ have both. Obviously, $P_{\mathcal{C}}$ is a complete metric space and thus the unique solution μ satisfies an exact and such that $\mu \in P_{\mathcal{C}}$ is strictly convex. Hence, it is possible now to conclude that $\mu \in P_{\mathcal{C}}$ is strictly increasing.

Lemma 2. The first part of the theorem is equivalent to the fact (2) covers the results of the end of [14, Chapter III, p. 10].

REFERENCES

- [1] M. S. Bazhuk, "Control System of a Ship's Roll, Design of Automatic Control, Moscow, 1961.

APPENDIX

1. TRANSFER FUNCTIONS OF THE SHIP'S ROLL CONTROL SYSTEM

Block Diagram

The block diagram of the control system is shown in Fig. 1. The transfer function of the system is given by the expression

$$W(s) = \frac{K_1 K_2 (s + a)}{s^2 + 2\zeta\omega_n s + \omega_n^2} \quad (1)$$

where K_1 is the gain of the amplifier; K_2 is the gain of the motor; a is the zero of the system; ζ is the damping coefficient; ω_n is the natural frequency of the system.

The transfer function of the system is given by the expression

$$W(s) = \frac{K_1 K_2 (s + a)}{s^2 + 2\zeta\omega_n s + \omega_n^2} \quad (2)$$

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$$W(s) = \frac{K_1 K_2 (s + a)}{s^2 + 2\zeta\omega_n s + \omega_n^2} \quad (7)$$

The transfer function of the system is given by the expression

$$W(s) = \frac{K_1 K_2 (s + a)}{s^2 + 2\zeta\omega_n s + \omega_n^2} \quad (8)$$

The transfer function of the system is given by the expression

$$W(s) = \frac{K_1 K_2 (s + a)}{s^2 + 2\zeta\omega_n s + \omega_n^2} \quad (9)$$